

**PREMIER PLATINUM INFRARED  
MID-RANGE CARBON DIOXIDE SENSOR**

Exd Certified versions

**\*\*\* Available in EN50271 / SIL1 Certified versions \*\*\***

SIL1



**MSH-PS/MCO2  
MSHia-PS/MCO2**

Non - SIL



**MSH-P/MCO2P  
MSHia-P/MCO2P**

**FEATURES**

- ★ Range 0-10% volume CO<sub>2</sub> to bridge the gap between the 0-5% and 0-100% CO<sub>2</sub> sensors.
- ★ Offers reduced response times when compared with earlier versions.
- ★ Contains all the necessary optics, electronics and firmware to provide a linearised, temperature-compensated output.
- ★ Choice of output format – digital output (floating point and binary), direct pellistor replacement or industry standard 0.4 to 2 volts.
- ★ User configurable using USB powered Premier Configuration Unit.
- ★ Analogue output is scaleable in % volume or % of the full scale.
- ★ Enhanced EMC protection
- ★ Internal Flash memory allowing sensor firmware updates via configuration equipment.

**Dynamant Limited**

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## DESCRIPTION

Dynamant infrared sensors operate by using the NDIR principle to monitor the presence of the target gas. The sensor contains a long life tungsten filament infrared light source, an optical cavity into which gas diffuses, a dual temperature compensated pyroelectric infrared detector, an integral semiconductor temperature sensor and electronics to process the signals from the pyroelectric detector .

Two versions are available:-

### **3 Pin Version - Pellistor Replacement Infrared**

These sensors provide a pellistor style linearised, temperature-compensated output as shown in Graph 1.

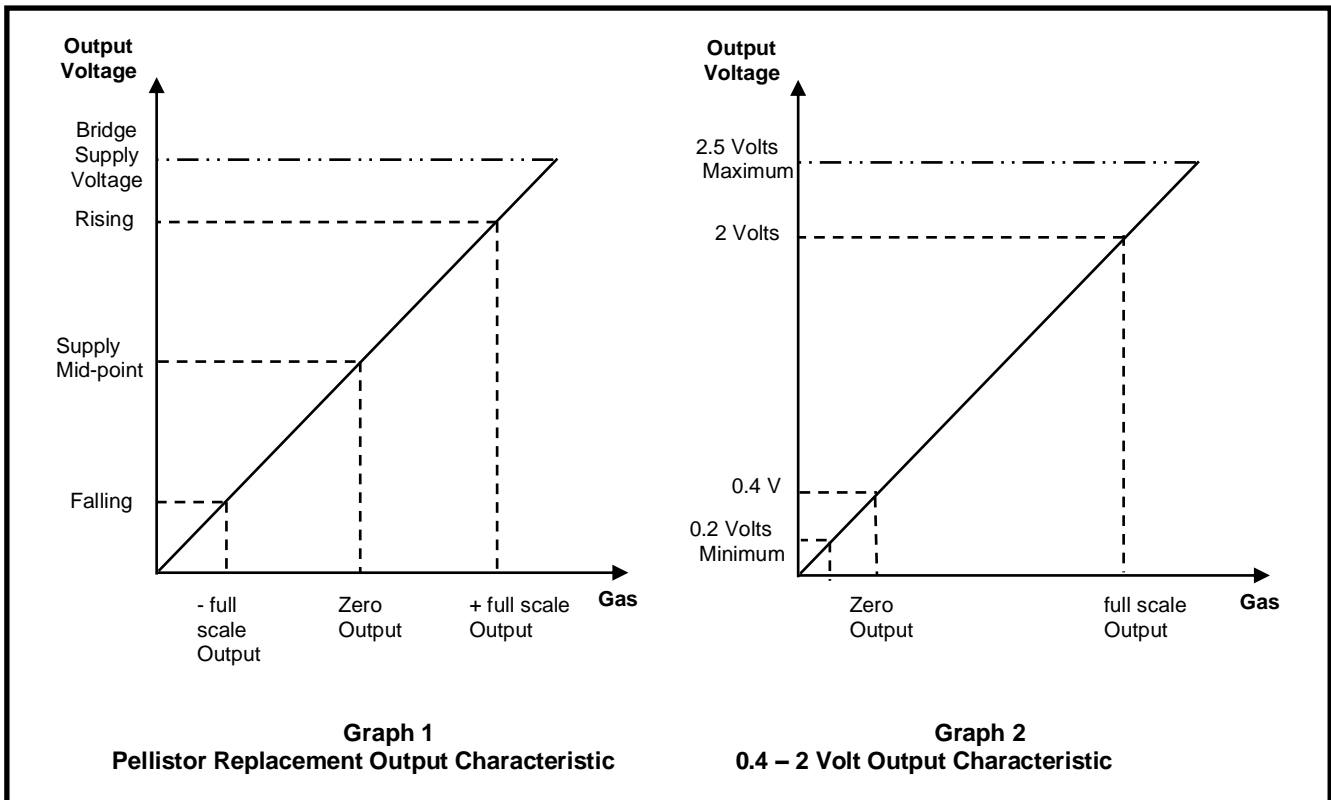
They can either be supplied pre-set to customer specification or may be configured by the user by means of a configuration unit available from Dynamant Ltd. The output signal can be set to rise or fall with increase in the gas level.

### **5 Pin Version - Multi-Purpose Range**

This version of the sensor provides maximum user flexibility by providing the following output options:-

- ★ Industry Standard 0.4 to 2 volt linearised, temperature-compensated output as shown in Graph 2, or alternative voltages for zero and full-scale outputs.
- ★ Digital output for direct communications with instrument electronics.
- ★ Rising or falling output with increasing gas level for the pellistor replacement, bridge output as shown in graph 1.

The digital output is a UART format comprising 8 data bits, 1 stop bit and no parity. Refer to specification for available baud rates. Contact Dynamant Ltd for protocol details.



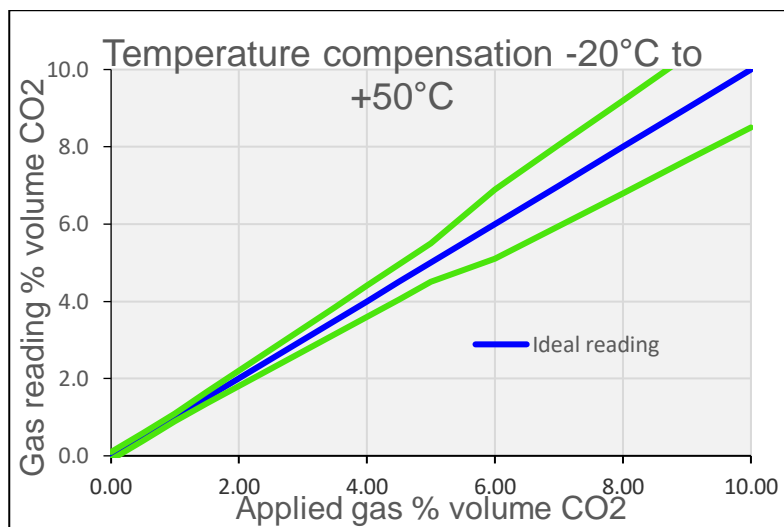
## Patent Protection

The sensor design is protected by the following Patents

Great Britain	GB 2 401 432 & GB 2 403 291
Europe	EP 1544603 & EP 1818667-Pending
France	EP [ FR ] 1544603
Germany	EP [ DE ] 1544603
Italy	EP [ I ] 1544603
Switzerland	EP [ CH ] 1544603
USA	7, 244, 939
Other World Patents	Pending

## Carbon dioxide Temperature Compensation

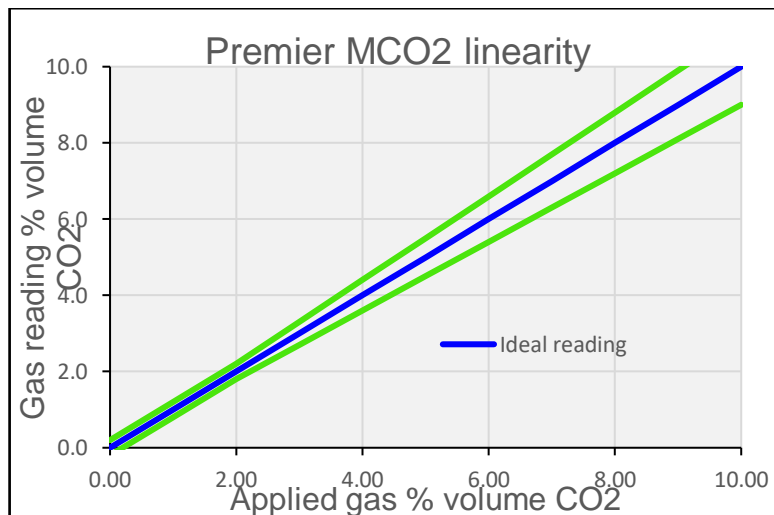
The Premier sensor is temperature compensated over the range of -20°C to +50°C. The output variation is  $\pm 0.1\%$  v/v or  $\pm 10\%$  of the applied gas up to 50% full scale and  $\pm 15\%$  of the applied gas from 50% to 100% full scale, whichever is greater.



## Carbon dioxide Linearity

The Premier sensor linearity at ambient temperature is  $\pm 2\%$  full scale or  $\pm 10\%$  of the applied gas whichever is greater.

The following graph is based on the 0-10% v/v sensor, data for 24 sensors.



## **Calibration options**

Dynamant recommend a maximum interval of 12 months between calibration checks. A small amount of zero drift can be accommodated by re-zeroing the gas detector against the sensor. The degree of drift that is acceptable should be determined by the user. Note that the subsequent change in gas reading will be greater than the change in zero reading.

If the sensor requires either a “Zero” or “Span” adjustment, there are two methods that can be used:

1) By using the “Premier Configuration Unit”

When used in conjunction with dedicated PC software, this device uses the data communication pins on the sensor to provide a means of calibration.

2) By using the data communications pins and software written in accordance with the protocol supplied by Dynamant.

Gas calibration is best carried out at 50% of the range. Other calibration levels, between 10% and 100% of the range can be used but may affect the accuracy of the readings.

If the calibration gas level is entered incorrectly for any range, there will be an error in the calibration. It is the user’s responsibility to ensure that the calibration procedure is correctly applied. Checks on the correct calibration gas level that are used during span operations should be implemented within the calibration routine of the host gas detector’s firmware.

**Note:** a zero calibration must always be carried out before a span calibration.

## **Sensor warm-up time**

When power is first applied to the sensor, the voltage at the output pin is held at a pre-determined level. The default setting for this start-up value is the “zero gas” value. This condition is maintained for a default “warm-up” time of 45 seconds, after this time the output voltage represents the calculated gas value. Sensors can take up to 1 minute to indicate the correct gas reading.

Note: the sensor can calculate any reading from -100% FSD to +200% FSD in the first minute. The output value that is read using the communications pins is always held at -250% FSD during the “warm-up” time.

Both the voltage at the output pin during the “warm-up” time, and the duration of the “warm-up” time can be pre-programmed to alternative values at the time of ordering sensors.

## **Temperature transients and gas flow rates.**

The Premier sensor employs a pyroelectric detector, the output from which can be disrupted by sudden changes in temperature. If there is an excessive change in the ambient temperature, gas sample temperature or flow rate, then the output signal will be momentarily frozen. Correct operation is restored when the effects of the transient have settled. Rates of change in the ambient temperature should be restricted to 2°C/minute and gas flow rates kept below 600 cc/minute.

## **Power supply considerations**

The sensor power supply rise time must be less than 50 mS to ensure correct operation. Operation outside the range of 3 – 5 V dc will result in either fault indication, or the sensor will not function correctly.

## **Sensor over-range condition**

The sensor will continue to provide an output up to a pre-determined percentage of the full scale value; at this point the reading is clamped, regardless of any further increase in detected gas level. The over-range value should be specified when ordering; choose from the following values 100%, 125%, 150% and 200% The linearity of the output is only guaranteed up to the full scale for the sensor; the over-range condition for the host instrument should therefore be determined by the user.

## **Sensor fault indication**

The sensor constantly performs checks on the internal memory contents, the incoming supply voltage and the analogue signal values. These checks are used to ensure that the sensor is operating within its correct parameters, and that no internal faults have developed.

If a fault condition is detected:

- 1) the output will be set to 0V.
- 2) The output value that is read when using the communications pins, instead of the voltage output pin, will be set to -250% full-scale.

As mentioned in the “Sensor warm-up time” section above, the voltage at the output pin during the warm-up time can be specified when ordering sensors.

## **Digital interface**

The digital communication pins “RX” and “TX” operate at a 2.8V logic level. When interfacing to external circuitry that uses a higher voltage level it is necessary to limit the current that can flow. The external voltage level should be 5V maximum and a 3K3 resistor should be used in series with each communication pin.

The Rx and Tx voltage limits are as follows:

RX - VIH: Input ‘High’ minimum voltage -  $0.8 V_{DD} = 2.24V$

RX - VIL: Input ‘Low’ maximum voltage -  $0.2 V_{DD} = 0.56V$

TX - VOH: Output ‘High’ minimum voltage -  $V_{DD} - 0.7 = 2.1$

TX - VOL: Output ‘Low’ maximum voltage - 0.6V

Contact Dynament Ltd for details of the required protocol.

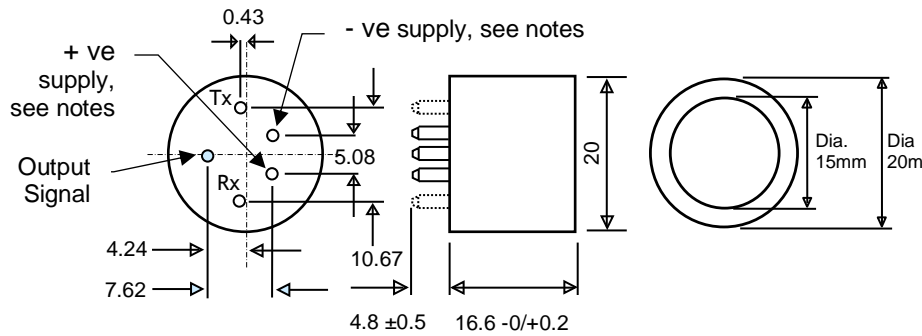
## SPECIFICATION @ 20°C (68°F) ambient temperature

<b>Operating Voltage Range:</b>	3.0 – 5.0 V d.c.
<b>Operating Current:</b>	Average current 15mA. See graph on page 5
<b>Programmable Output Voltage Ranges:</b>	Voltage Output Types – 0.2V to 2.5V d.c. Bridge Output Types – 0v to Bridge Supply Voltage
<b>Volume measuring range:</b>	0-10% volume CO <sub>2</sub>
<b>Resolution:</b>	0.01% Output voltage resolution 42.7 μV.
<b>Linearity:</b>	The output is linear within ± 2% of full scale, or ± 10% of the applied gas, whichever is greater.
<b>Warm up time:</b>	To final zero ± 2% full-scale: approximately 1 minute, some sensors may take longer.
<b>Accuracy:</b> At calibration gas level ( <i>refer to calibration certificate</i> )	± 10% at 1 bar pressure and 20°C
<b>Pressure</b>	± 5% of the calibration pressure to maintain the accuracy limits
<b>Response Time T<sub>50</sub>:</b>	<15s
<b>Response Time T<sub>90</sub>:</b>	<30s
<b>Zero Repeatability:</b>	± 2% of full scale
<b>Span Repeatability:</b>	± 2% of full scale
<b>Long term zero drift:</b>	± 1% of full scale / month
<b>Operating temperature range:</b>	-20°C to +50°C (-4°F to 122°F)
<b>Temperature performance over the range -20°C to +50°C(-4°F to 122°F):</b>	± 10% of applied gas up to 50% of the full scale and ± 15% of applied gas from 50% to 100% of the full scale.
<b>Storage temperature range:</b>	-20°C to +50°C (-4°F to 122°F)
<b>Humidity range:</b>	0 to 95% RH non-condensing.
<b>Digital signal format:</b>	8 data bits, 1 stop bit, no parity. 2.8V logic level
<b>Standard baud rates:</b>	38,400, 19,200, 9600, 4800
<b>User configurable parameters and functions:</b>	Zero output voltage Full-scale output voltage Positive or negative going output Sensor 'zero' function Sensor 'span' function Over-range value
<b>MTBF:</b>	> 5 years
<b>Weight :</b>	15 grams

<b>CERTIFICATION DETAILS</b>		
<b>European ATEX Certification</b>	<b>Sensor types MSH-P, MSH-PS</b>	<b>Sensor types MSHia-P, MSHia-PS</b>
<b>Approval body</b>	<b>SIRA</b>	
<b>Certificate Number</b>	<b>SIRA 04ATEX1357U (Ex &amp; EN50271 / SIL1)</b>	
<b>Test Standards</b>	<b>EN60079-0:2012+A11:2013, EN60079-1:2014, EN60079-11:2012, EN60079-26:2015 EN 50271:2010</b>	
<b>Certification Codes</b>	<b>I M2 Ex db I Mb II 2 G Ex db IIC Gb</b>	<b>I M2 Ex db I Mb II 2 G Ex db IIC Gb</b>
<b>Input parameters</b>	<b>0.8W max, 30V max. (See footnote)</b>	<b>0.8W max, 30V max. (See footnote)</b>
<b>Operating temperature</b>	<b>-20°C to +60°C (See footnote)</b>	
<b>International IECEx Certification</b>	<b>Sensor types MSH-P, MSH-PS</b>	<b>Sensor types MSH-P, MSH-PS</b>
<b>Approval body</b>	<b>SIRA</b>	
<b>Certificate Number</b>	<b>IECEX SIR 05.0053U</b>	
<b>Test Standards</b>	<b>IEC 60079-0:2011 IEC60079-1:2014 IEC 60079-11:2011 EN 60079-26:2014</b>	
<b>Certification Codes</b>	<b>Ex db I and/or Ex db IIC</b>	<b>Ex db I and/or Ex db IIC</b>
<b>Input parameters</b>	<b>0.8W max, 30V max.</b>	<b>0.8W max, 30V max.</b>
<b>Operating temperature</b>	<b>-20°C to +60°C (See footnote)</b>	
<b>North American Certification</b>	<b>Sensor type MSH-P</b>	<b>Sensor type MSHia-P</b>
<b>Approval body</b>	<b>Underwriters Laboratory Inc.</b>	<b>Underwriters Laboratory Inc.</b>
<b>File Reference</b>	<b>E336365</b>	<b>E336365</b>
<b>Test Standards</b>	<b>UL 60079 – 0, 4<sup>th</sup> Edition UL 60079 - 1, 6<sup>th</sup> Edition CAN/CSA-C22.2 No. 60079-0-1-7 CAN/CSA-C22.2 No. 60079-1 part 1, 1<sup>st</sup> Edition</b>	<b>UL913 7<sup>th</sup>, Edition UL 60079 – 0, 4<sup>th</sup>, Edition UL 60079 – 11, 2<sup>nd</sup>, Edition CAN/CSA-C22.2 No. 157-92</b>
<b>Hazardous Locations</b>	<b>Class 1, Zone 1, AEx d IIC and Ex d IIC Hazardous Locations</b>	<b>Class I, II, III, Division 1  Class 1, Zone 0, AEx ia IIC, T4 with 60°C ambient</b>
<b>Input/Entity parameters</b>	<b>0.8W max, 30V max.</b>	<b>Ui=6V dc, Pi=0.8W, Ci=4.105µF, Li=0 mH</b>
<b>Input parameters are defined for certification purposes only, refer to the “Specification” table for the sensor operating voltage and temperature range.</b>		

## MECHANICAL DETAIL

## NOTES



1. TOLERANCE: +/- 0.15 UNLESS OTHERWISE STATED.
2. RECOMMENDED PCB SOCKET  
WEARNES CAMBION LTD  
CODE: 450-3326-01-06-00.
3. **USE ANTI-STATIC PRECAUTIONS WHEN HANDLING**
4. **DO NOT CUT PINS**
5. **DO NOT SOLDER DIRECTLY TO PINS**
6. THE LABELLING ADDS UP TO 0.2 TO THE OUTER DIAMETER, AND UP TO 0.2 TO THE OVERALL HEIGHT

All dimensions are in millimetres. Pins viewed from underside  
Diameter of pins = 1.5 +/- 0.05  
Tx & Rx communication connections are available as either pads or pins

**NOTE – The above pin configuration is shown for the POSITIVE version of the sensor. The NEGATIVE version has the +ve and –ve supply pin positions exchanged. See ordering details.**

### Warranty information

All Dynament Premier sensors carry a five-year warranty against defects in materials and workmanship. The warranty is invalidated if the sensors are used under conditions other than those specified in this data sheet.

Particular attention should be paid to the following criteria:

- **Observe the correct supply polarity**
- **Do not exceed the maximum rated supply voltage of 5V**
- **Do not solder directly to the sensor pins**
- **Do not expose the sensor to corrosive gases such as hydrogen sulphide**
- **Do not allow condensation to take place within the sensor**

Dynament reserve the right to alter technical specifications, without prior notice, when it is appropriate to implement a technical enhancement that leads to improved performance. Should any changes be required that could affect the customer's use of the product, Dynament will endeavour to contact customers directly to inform them of the changes.



## Ordering Details

In order to completely specify the type of sensor that is required, the customer needs to provide the following information:-

- An Order Code (see below) that specifies the sensors' basic physical and electrical characteristics.
- The sensor configuration requirements.

### EXAMPLE OF ORDER CODES

MSH – PS / MCO2 / 3 / B / P / F

**FILTER:**  
BLANK = OMITTED  
F = FITTED

**SUPPLY POLARITY:**  
P = Positive  
N = Negative

**OUTPUT TYPE :**  
B = Bridge,  
V = Voltage

**NUMBER OF PINS:**  
3, 4 or 5

**GAS TYPE:**  
MCO2 = Carbon Dioxide, SIL1  
MCO2P = Carbon Dioxide, Non-SIL1

**PLATINUM SENSOR:**  
P = Non-SIL1  
PS = SIL1

**MSHia**  
(For Mining M1 applications only)

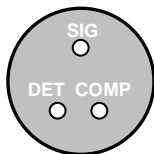
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### CONFIGURATION OPTIONS

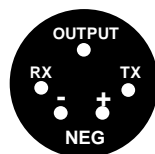
(To be stated on customer order in addition to the Order Code)

1. Output voltage for zero.
2. Output voltage for span.
3. Rising or falling output voltage with increasing gas level (for "Bridge" outputs)
4. Sensitivity e.g. 100 mV = 10 % volume CO<sub>2</sub> for "Bridge" outputs, 0.4 – 2.4V = 5% volume carbon dioxide for "Voltage" output sensors.
5. Communication speed – 38,400 baud (default), specify alternative rate if required.
6. Over-range value: 100%, 125%, 150% and 200% of full-scale value.

## Pellistor Replacement - Explanation of Positive & Negative Polarity

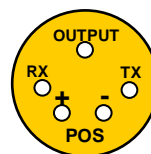


Typical Pellistor Pinout



**Premier Negative Polarity Option**

Use where the DET pin of the existing pellistor is connected to the Negative of the pellistor bridge supply.



**Premier Positive Polarity Option**

Use where DET pin of the existing pellistor is connected to the Positive of the pellistor bridge supply.

Note – On the 3 pin version of the sensor, the RX and TX connections are pads, not pins.